

**Claims: I claim:**

1. A massage and tactile stimulation device comprising a hand covering [constituting a flexible glove] made of a [any suitable] resilient material having a palm wall and a back wall, said walls connected by a means for joining two pieces of material, said glove having one or more predetermined upward projections secured at one or more effective working areas of the glove, [said projection being made of a rubber-like material providing a means for deep and point specific pressure to affect deeper tissues.] said projection attached to said glove by means providing for stationary bonding, said device being with [or without] one or more friction areas [made of a rubber-like material having a sufficient coefficient of friction to provide a means for imparting to the recipient improved manual manipulations, said friction area] attached to said glove at effective working areas by means providing for stationary bonding.
2. The glove of claim 1 wherein said resilient material is lycra or spandex.
3. The glove of claim 1 [2] wherein said means for joining 2 pieces of material is [includes] sewing.
4. [The glove of claim 3 wherein said rubber-like material of said projection is composed of polyurethane.] Cancelled
5. The glove of claim 1 [4] wherein said effective working area for said projection includes [include the pad] pads of digits, a palm, and a region of [the first row of] proximal phalanges.
6. The glove of claim 1 [5] wherein [said] stationary bonding for said projection[s] and said friction area is pressure sensitive adhesion.

7. [The glove of claim 6 wherein said projection and said friction area can be of any shape, predetermined size, color, form, and texture including smooth and pimpled, and be varied on the same said glove.] Cancelled.

8. A massage and tactile stimulation device for manual control and operation constructed of a flexible rubber-like material that contours to the anatomy of the underlying joints and part of body covered by said device, said device having one or more predetermined prominent projections made of a rubber-like material providing a means for deep and point specific pressure to affect deeper tissues of recipient of said device, said projections located at one or more effective working areas of said device, [said device being with or without one or more friction areas, said friction areas made of a rubber-like material having a sufficient coefficient of friction to provide a means for imparting to the recipient improved manual manipulations, said friction areas located at effective working areas of said device,]

9. The device of claim 8 wherein [said] parts of body covered by said device includes [include] one of the following: a [the] hand, an elbow, and a foot.

10. The device of claim 8 [9] wherein said effective working areas for said projections include [the] finger pads, knuckles, a palm, an elbow, and a sole of the foot.

whereby [said device will impart] deep pressure is imparted by [and improved manipulations to] said device [recipient],  
and

whereby said [manipulator of said device will utilize said projection] projections [and said friction area to] optimize the benefits of massage and tactile stimulation [to said recipient].